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Australia



Earth-moving machinery — Loaders — Terminology and commercial specifications



AS ISO 7131:2021

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- Institute of Instrumentation, Control & Automation Australia
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Earth-moving machinery — Loaders — Terminology and commercial specifications

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Preface

This Standard was prepared by the Standards Australia Committee ME-063, Earthmoving Equipment.

The objective of this document is to establish the terminology and content of commercial literature specifications for self-propelled crawler and wheeled loaders as defined in ISO 6165, with their equipment and attachments, used in earth-moving operations.

This document is identical with, and has been reproduced from, ISO 7131:2009, *Earth-moving machinery — Loaders — Terminology and commercial specifications*, and its Amendment 1 (2017), which has been added at the end of the source text.

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Foreword

ISO (the International Organization for Standardization) is a worldwide federation of national standards bodies (ISO member bodies). The work of preparing International Standards is normally carried out through ISO technical committees. Each member body interested in a subject for which a technical committee has been established has the right to be represented on that committee. International organizations, governmental and non-governmental, in liaison with ISO, also take part in the work. ISO collaborates closely with the International Electrotechnical Commission (IEC) on all matters of electrotechnical standardization.

International Standards are drafted in accordance with the rules given in the ISO/IEC Directives, Part 2.

The main task of technical committees is to prepare International Standards. Draft International Standards adopted by the technical committees are circulated to the member bodies for voting. Publication as an International Standard requires approval by at least 75 % of the member bodies casting a vote.

Attention is drawn to the possibility that some of the elements of this document may be the subject of patent rights. ISO shall not be held responsible for identifying any or all such patent rights.

ISO 7131 was prepared by Technical Committee ISO/TC 127, *Earth-moving machinery*, Subcommittee SC 4, *Terminology, commercial nomenclature, classification and rating*.

This third edition cancels and replaces the second edition (ISO 7131:1997), which has been technically revised.

Australian Standard[®]

Earth-moving machinery — Loaders — Terminology and commercial specifications

1 Scope

This International Standard establishes the terminology and content of commercial literature specifications for self-propelled crawler and wheeled loaders as defined in ISO 6165, with their equipment and attachments, used in earth-moving operations.

2 Normative references

The following referenced documents are indispensable for the application of this document. For dated references, only the edition cited applies. For undated references, the latest edition of the referenced document (including any amendments) applies.

ISO 3450, *Earth-moving machinery - Braking systems of rubber-tyred machines - Systems and performance requirements and test procedures*

ISO 6014, *Earth-moving machinery - Determination of ground speed*

ISO 6016:2008, *Earth-moving machinery - Methods of measuring the masses of whole machines, their equipment and components*

ISO 6165:2006, *Earth-moving machinery - Basic types - Identification and terms and definitions*

ISO 6746:2003 (all parts), *Earth-moving machinery - Definitions of dimensions and codes*

ISO 7457, *Earth-moving machinery - Measurement of turning dimensions of wheeled machines*

ISO 9249, *Earth-moving machinery - Engine test code - Net power*

ISO 10265, *Earth-moving machinery - Crawler machines - Performance requirements and test procedures for braking systems*

ISO 14396, *Reciprocating internal combustion engines - Determination and method for the measurement of engine power - Additional requirements for exhaust emission tests in accordance with ISO 8178*

ISO 14397-1, *Earth-moving machinery - Loaders and backhoe loaders - Part 1: Calculation of rated operating capacity and test method for verifying calculated tipping load*

ISO 14397-2, *Earth-moving machinery - Loaders and backhoe loaders - Part 2: Test method for measuring breakout forces and lift capacity maximum lift height*

3 Terms and definitions

For the purposes of this document, the terms and definitions given in ISO 6165, ISO 6746 and the following apply.

3.1 General

3.1.1 loader

self-propelled crawler or wheeled machine which has front-mounted equipment primarily designed for loading operation (bucket use) and which loads or excavates through forward motion of the machine

Note 1 to entry: A loader work cycle normally comprises filling, elevating, transporting and discharging of material.

[SOURCE: ISO 6165:2006, definition 4.2]

3.1.1.1

compact loader

loader (3.1.1) having an operating mass (3.2.1) of 4 500 kg or less, designed to work in confined spaces with the associated need for greater manoeuvrability

Note 1 to entry: The general term *compact machine* is defined in ISO 6165.

3.1.1.2

skid steer loader

loader (3.1.1) which normally has an operator station between attachment-supporting structures and which is steered by using variation of speed, and/or direction of rotation between traction drives on the opposite sides of a machine having fixed axles on wheels or tracks

[SOURCE: ISO 6165:2006, definition 4.2.2]

3.1.2

base machine

machine with a cab or canopy and operator-protective structures if required, without equipment or attachments but possessing the necessary mountings for such equipment and attachments

[SOURCE: ISO 6746-1:2003, definition 3.3]

Note 1 to entry: The machine will need to be provided with the necessary mountings to secure equipment and attachments (see [Clause 5](#)).

3.2 Masses

3.2.1

operating mass

OM

mass of the *base machine* (3.1.2), with equipment and empty *attachment* (3.3.1) in the most usual configuration as specified by the manufacturer, and with the operator (75 kg), full fuel tank and all fluid systems (i.e. hydraulic oil, transmission oil, engine oil, engine coolant) at the levels specified by the manufacturer and, when applicable, with sprinkler water tank(s) half full

Note 1 to entry: The mass of an operator is not included for non-riding machines.

Note 2 to entry: Ballast mass at delivery can be included if specified by the manufacturer.

[SOURCE: ISO 6016:2008, definition 3.2.1]

3.2.2

shipping mass

SM

mass of the base machine without an operator, and with fuel level at 10 % of tank capacity or with the minimum fuel level needed for machine shipping purposes as specified by the manufacturer, whichever is higher, with all fluid systems at the levels specified by the manufacturer, and with empty sprinkler tank(s), if required, and with or without equipment, ballast, attachment, cab, canopy, operator-protective structures, wheels and counterweights as stated by the manufacturer

Note 1 to entry: If the manufacturer intends that the machine be partially disassembled for shipping purposes, the masses of the disassembled items will also be stated.

[SOURCE: ISO 6016:2008, definition 3.2.6]

3.3 Attachments

3.3.1

attachment

assembly of components that can be mounted onto the *base machine* (3.1.2) or equipment for specific use

[SOURCE: ISO 6746-2:2003, definition 3.5]

3.3.1.1

backhoe

attachment (3.3.1) which generally excavates towards the machine and below ground level, and which elevates, swings and dumps material by the action of a boom, arm and bucket

Note 1 to entry: For dedicated backhoe loaders, see ISO 8812.

3.3.1.2

scarifier

attachment (3.3.1) having teeth for penetrating and loosening to shallow depths materials such as earth, asphalt and gravel for roads and for similar functions

See [Figure 19](#)

Note 1 to entry: It is usually mounted on the back of the loader but can be mounted on the back of the bucket.

3.3.2

side dump bucket

bucket which loads through forward motion of the machine and which can dump to the side from an end, or dump forwards

See [Figure 17](#)

3.3.3

multi-purpose bucket

bucket having a dozer-type mouldboard with hinges at the top to support a clam which can be opened to various positions, providing for use as a dozer, scraper, clam or bucket

See [Figure 17](#)

3.3.4

fork arm

structure having tines for lifting, transporting and discharging warehouse-type pallets

See [Figure 22](#)

Note 1 to entry: When the fork attachment is fitted to a loader, the machine is still classified as an earth-moving machine, not a rough terrain fork truck.

3.3.5

log fork

log grapple

mechanism having tines and a top clamp for lifting, transporting, and discharging logs

See [Figure 23](#)

3.3.6

winch

frame equipped with a drum and connected to the rear part of the *base machine* (3.1.2)

See [Figure 24](#)

3.4

equipment

set of components mounted onto the base of the machine to provide the primary design function of the loader

4 Base machine

4.1 Types of loader

Loaders shall be classified by type of attribute: according to their undercarriage, engine location, and steering and drive systems.

4.1.1 Undercarriage

4.1.1.1 Crawler loader (see [Figure 1](#))



Figure 1 — Crawler loader

4.1.1.2 Wheeled loader (see [Figure 2](#))



Figure 2 — Wheeled loader

4.1.2 Engine location

4.1.2.1 Front engine (see [Figure 3](#))

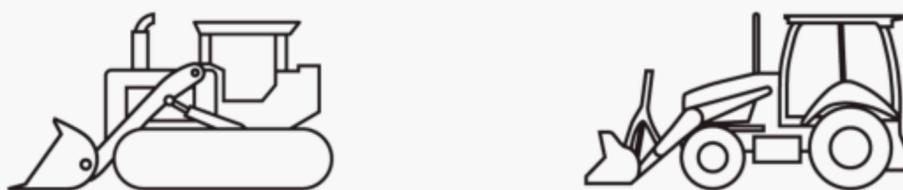


Figure 3 — Front engine

4.1.2.2 Rear engine (see [Figure 4](#))

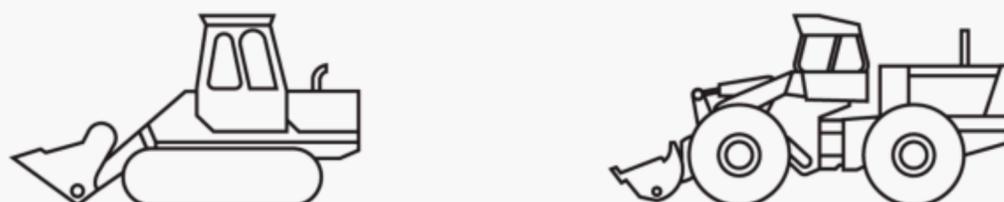


Figure 4 — Rear engine

4.1.3 Steering system

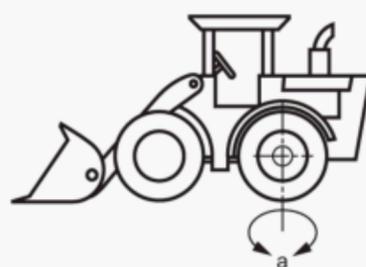
4.1.3.1 Front-wheel steer (see [Figure 5](#))



a Steerable wheels.

Figure 5 — Front-wheel steer

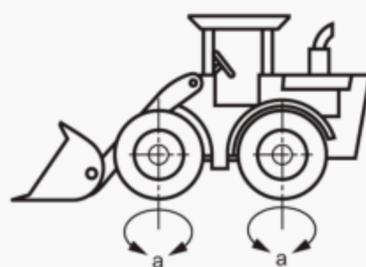
4.1.3.2 Rear-wheel steer (see [Figure 6](#))



a Steerable wheels.

Figure 6 — Rear-wheel steer

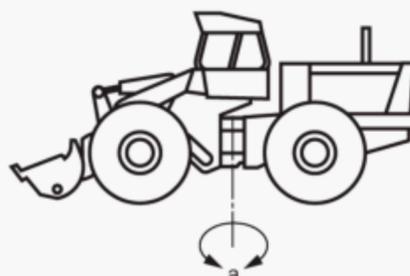
4.1.3.3 All-wheel steer (see [Figure 7](#))



a Steerable wheels.

Figure 7 — All-wheel steer

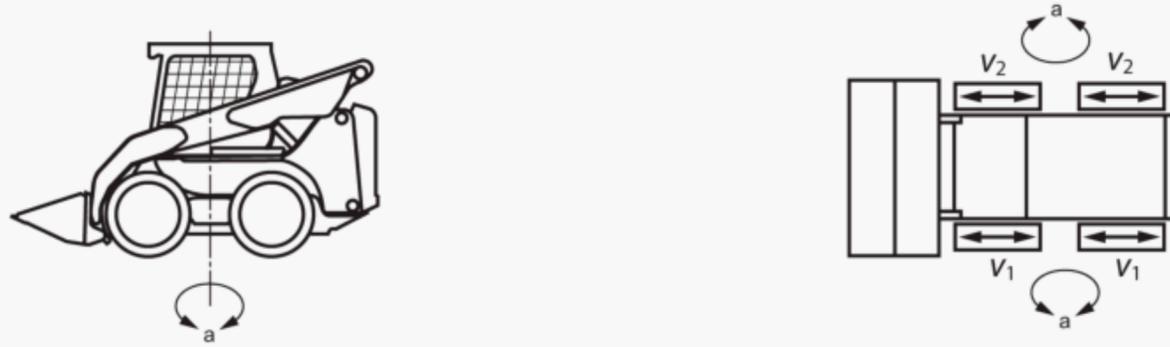
4.1.3.4 Articulated steer (see [Figure 8](#))



a Turning centre.

Figure 8 — Articulated steer

4.1.3.5 Wheel-skid steer (see [Figure 9](#))



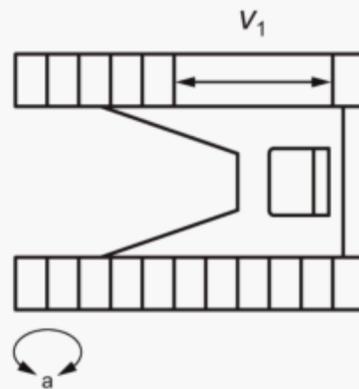
Key

v wheel velocity ($v_1 \neq v_2$)

a Turning centre.

Figure 9 — Wheel skid steer

4.1.3.6 Crawler pivot steer (see [Figure 10](#))



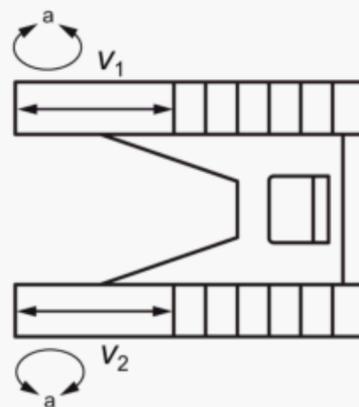
Key

v_1 track velocity

a Steerable pivot.

Figure 10 — Crawler pivot steer

4.1.3.7 Crawler independent steer or crawler skid steer (see [Figure 11](#))



Key

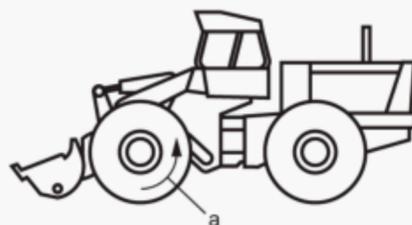
v track velocity ($v_1 \neq v_2$)

a Steerable track.

Figure 11 — Crawler independent steer or crawler skid steer

4.1.4 Drive system

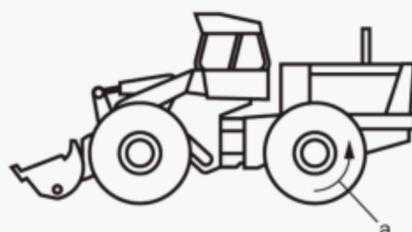
4.1.4.1 Front-wheel drive (see [Figure 12](#))



a Drive wheels.

Figure 12 — Front-wheel drive

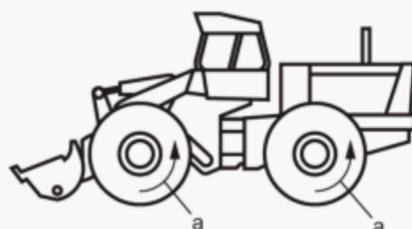
4.1.4.2 Rear-wheel drive (see [Figure 13](#))



a Drive wheels.

Figure 13 — Rear-wheel drive

4.1.4.3 All-wheel drive (see [Figure 14](#))

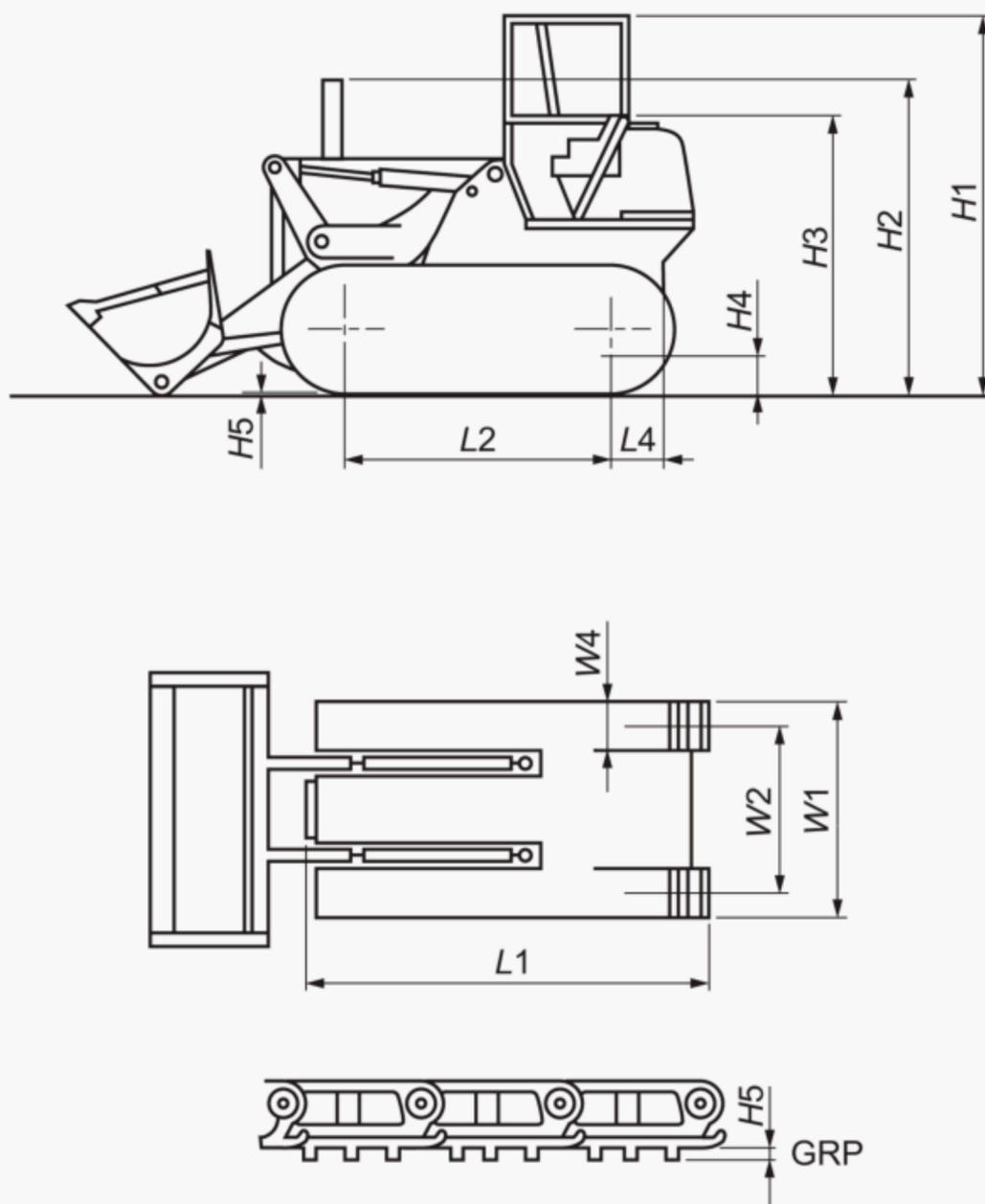


a Drive wheels.

Figure 14 — All-wheel drive

4.2 Dimensions

Figure 15 shows the base machine dimensions on a crawler loader.



Key

GRP ground reference plane

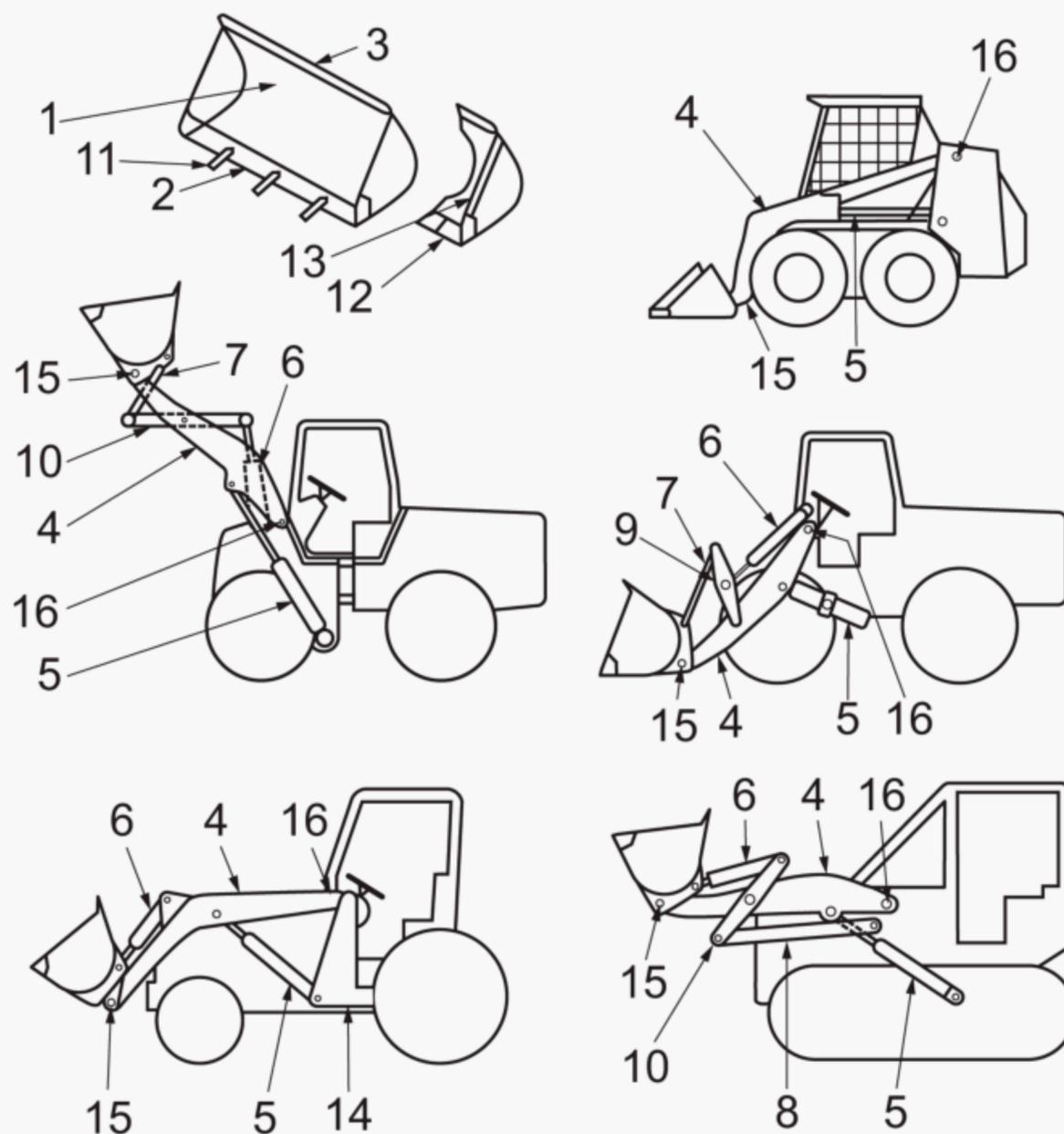
For the definition of the dimensions, see ISO 6746-1.

Figure 15 — Base machine dimensions (crawler loader)

5 Equipment and attachments

5.1 Nomenclature

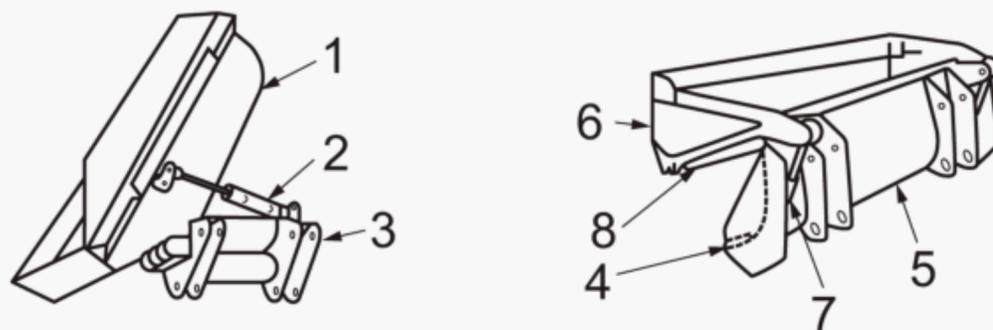
See [Figures 16](#) and [17](#).



Key

1	bucket	9	lever, bucket
2	cutting edge	10	link, Z-bar
3	spill guard	11	tooth, bucket
4	lift arm	12	cutter, corner
5	cylinder, lift	13	cutter, side
6	cylinder, bucket	14	frame, loader (where separate from machine main frame)
7	link, bucket	15	pin, bucket hinge
8	link, guide	16	pin, lift arm hinge

Figure 16 — Loader equipment and attachment nomenclature

**Key**

- 1 bucket
- 2 cylinder, side dump
- 3 bucket support with carrier
- 4 cutting edge, mouldboard
- 5 mouldboard
- 6 clam section
- 7 cylinder, clam
- 8 clam cutting edge

Figure 17 — Loader attachment nomenclature

5.2 Dimensions

Figures 18 to 24 show the dimensions of the various equipment and attachments that can be installed on loaders.

See Annex A for the definitions of the dimensions.

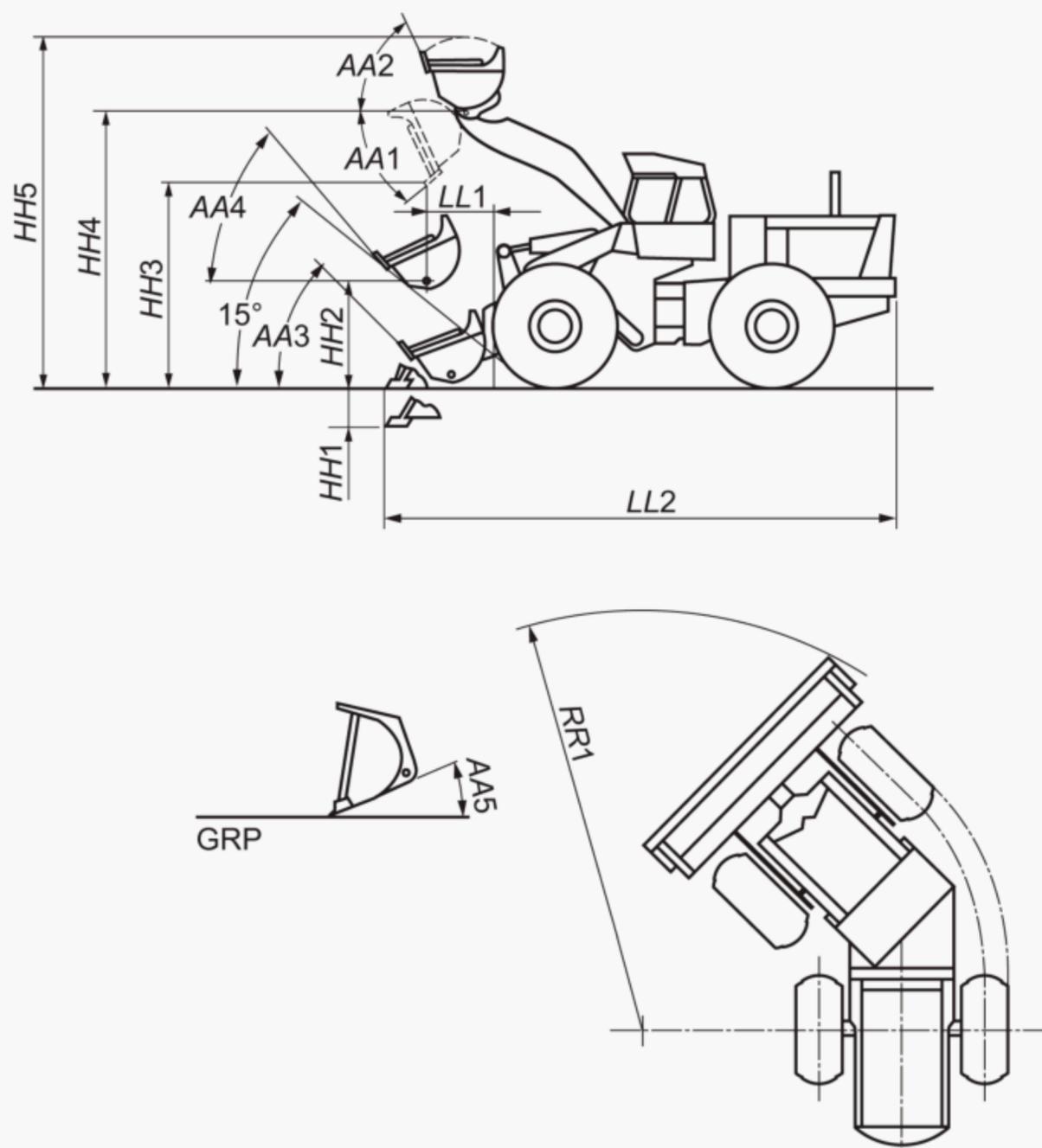


Figure 18 — Dimensions of equipment and bucket installed on loaders

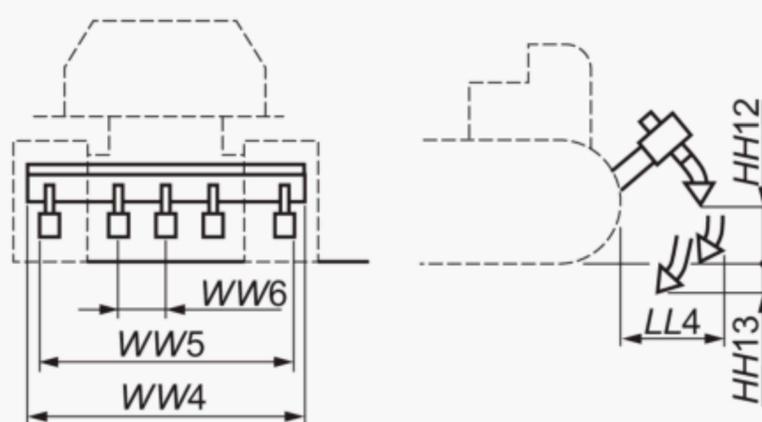


Figure 19 — Dimensions of equipment and scarifier installed on loaders

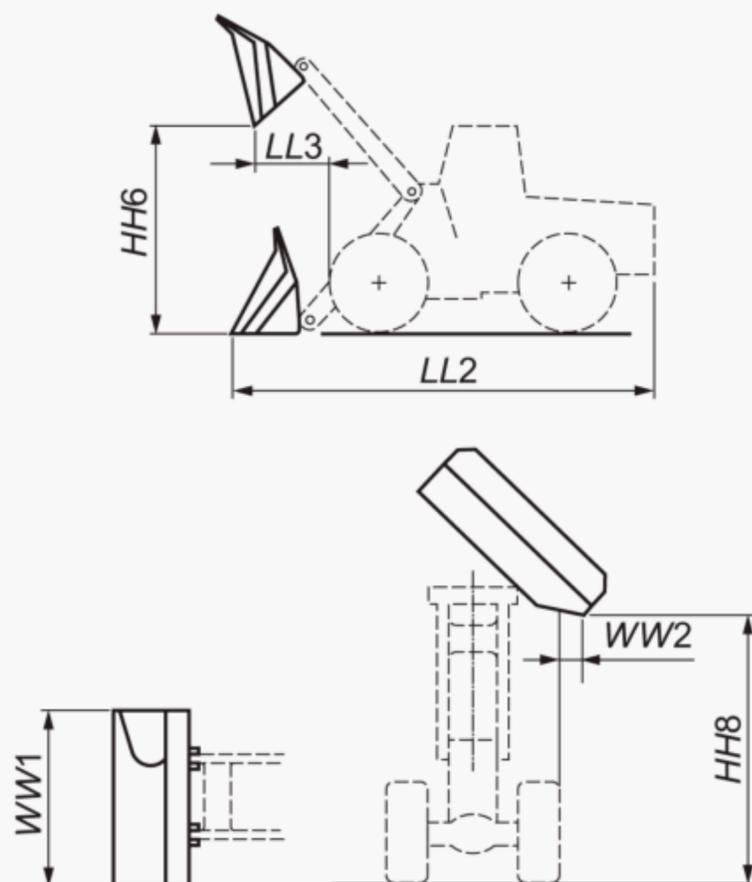


Figure 20 — Dimensions of equipment and side dump bucket installed on loaders

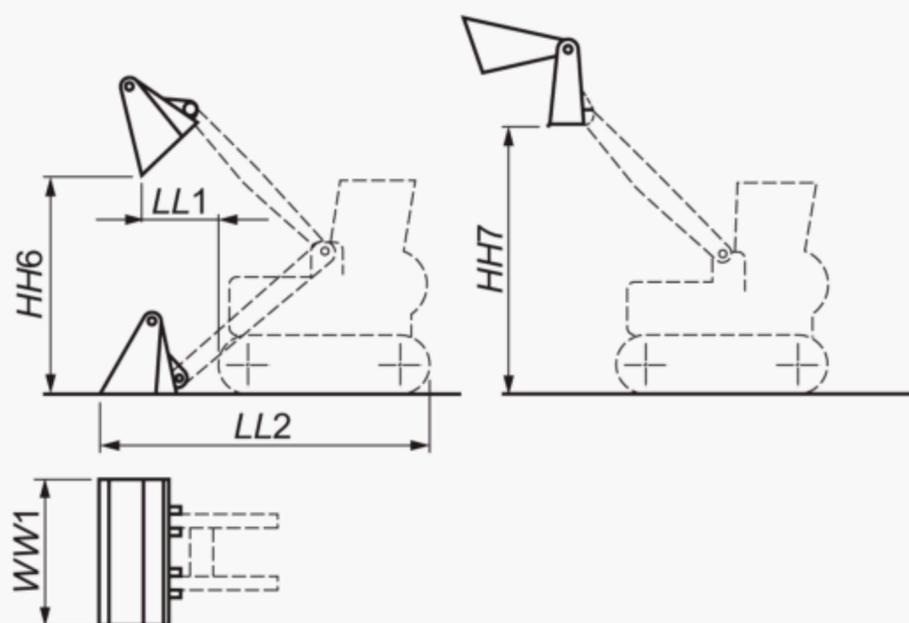


Figure 21 — Dimensions of equipment and multi-purpose bucket installed on loaders

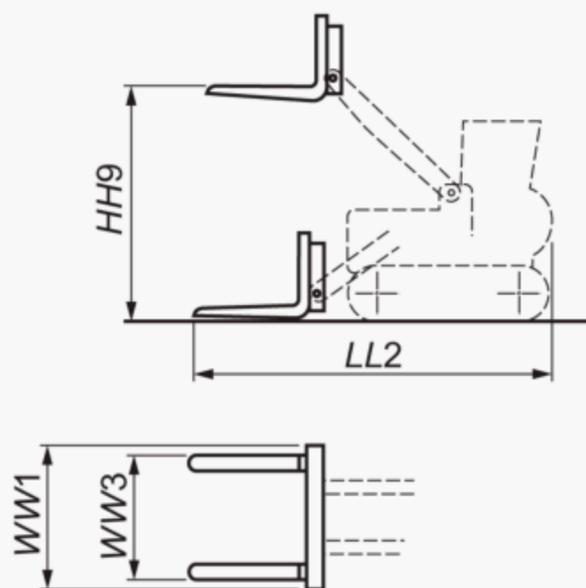


Figure 22 — Dimensions of equipment and fork installed on loaders

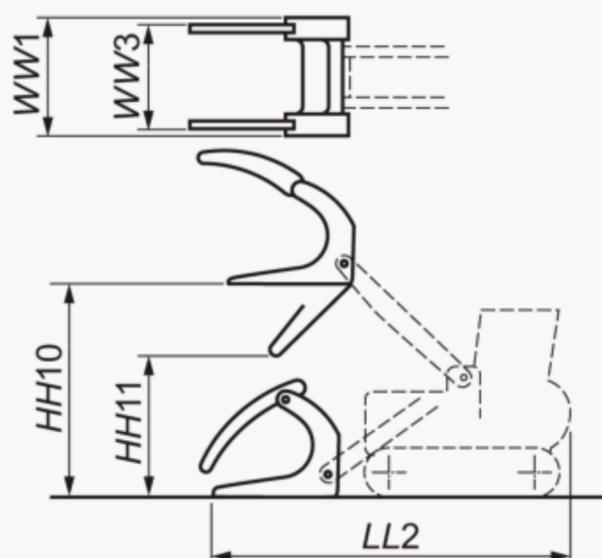


Figure 23 — Dimensions of equipment and log fork [log grapple] installed on loaders

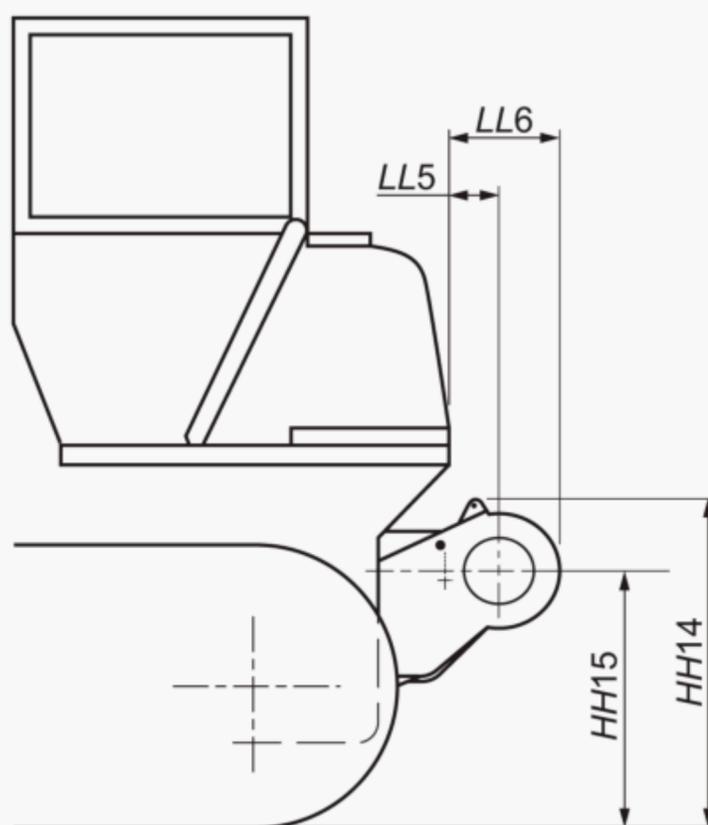


Figure 24 — Dimensions of equipment and winch installed on loaders

6 Performance terminology

6.1 Net power (engine)

See ISO 9249 and ISO 14396.

6.2 Tipping load at maximum reach

See ISO 14397-2.

6.3 Lift capacity to maximum height

See ISO 14397-2.

6.4 Rated operating capacity

See ISO 14397-1.

6.5 Breakout force

See ISO 14397-2.

6.6 Raising time

This is the minimum time required to raise the empty bucket with the stated operating load from the lowest position possible and fully rolled back to full height.

6.7 Lowering time

This is the minimum time required to lower the empty bucket from full height to the lowest possible position with the bucket bottom lying on the ground reference plane (GRP).

6.8 Dump time

This is the minimum time required to rotate the bucket from the maximum rollback - not exceeding the horizontal strike plane - fully raised position to the full dump position while dumping an operating load.

6.9 Maximum travel speeds

These are the maximum speeds that can be obtained on a hard level surface in each of the forward and reverse gear ratios with the bucket empty (see ISO 6014).

6.10 Braking performance

6.10.1 See ISO 3450 for wheeled loaders.

6.10.2 See ISO 10265 for crawler loaders.

6.11 Turning radius

See ISO 7457.

6.12 Lift capacity to maximum height

See ISO 14397-2.

7 Commercial literature specifications

7.1 General

This clause defines the information to be specified in the commercial literature.

SI (international system) units shall be used.

The following characteristics can be affected by bucket selection on machines equipped with non-standard tyres:

- bucket capacity (nominal heaped);
- overall operating height;
- overall length;
- dump angle;
- dump height;
- reach, fully raised;
- rollback (specify height);
- maximum rollback at ground;
- carry position;
- maximum rollback at carry position;
- digging depth;
- bucket width;
- maximum grading angle;
- operating mass¹⁾;
- operating load;
- tipping load²⁾;
- tipping load (at specified height)³⁾;
- breakout force⁴⁾;
- machine clearance radius⁵⁾.

7.2 Engine

The following information shall be specified:

- a) ignition type, i.e. diesel or spark-ignition;
- b) form of air aspiration, i.e. naturally aspirated, mechanically supercharged or turbocharged;

1) Can be further affected by tyre selection, tyre ballast, counterweight or attachments.

2) Can be further affected by tyre selection, tyre ballast, counterweight or attachments.

3) Can be further affected by tyre selection, tyre ballast, counterweight or attachments.

4) Can be further affected by tyre selection, tyre ballast, counterweight or attachments.

5) Can be further affected by tyre selection.

c) number of cylinders.

Other information that may also be specified includes

- d) manufacturer and model,
- e) type of cycle, i.e. two- or four-stroke,
- f) bore,
- g) stroke,
- h) displacement,
- i) net flywheel power at a given engine speed,
- j) maximum torque at a given engine speed,
- k) cooling system, i.e. air- or liquid-cooled,
- l) fuel type,
- m) starter type, and
- n) electrical system voltage.

7.3 Transmission

The transmission type shall be specified.

EXAMPLE Manual shift with flywheel clutch, powershift with torque converter, hydrostatic, electric.

Other information that may be specified in relation to the transmission includes

- number of speeds (forward and reverse), and
- maximum travel speeds (forward, reverse).

7.4 Hydraulic system

The following shall be specified:

- a) pump flow at a given pressure, at given engine speed;
- b) maximum normal system operating pressure.

Other additional hydraulic-system-related information may also be specified.

7.5 Filtration system

The type of filtration system may be specified.

7.6 Brakes

The following may be specified:

- a) type and actuating system of
 - 1) service brakes,
 - parking brakes, and

- (iii) secondary brakes;
- b) brake performance.

7.7 Additional information for crawler loaders

7.7.1 Steering

The type of steering shall be specified.

7.7.2 Final drive

The type of final drive may be specified.

EXAMPLE Type (single or double reduction, planetary), ratio, lubrication.

7.7.3 Track

The following shall be specified:

- a) type;
- b) dimensions.

The following may also be specified:

- c) ground contact area;
- d) number of shoes (each side);
- e) number of carrier rollers (each side);
- f) number of track rollers (each side).

7.8 Additional information for wheeled loaders

7.8.1 Driving axle

The type of driving axle may be specified.

EXAMPLE Fixed versus oscillating, bevel gear and pinion, differential, two-speed, hydrostatic, planetary final drive.

7.8.2 Steering

The type of steering shall be specified.

Other related information that may be specified includes

- turning radius (left and right),
- articulation angle, and
- machine clearance diameter.

7.8.3 Tyres

The size and type of the tyres shall be specified.

Other related information that may be specified includes

- a) tread,
- b) ply rating, and
- c) rim size.

7.9 System fluid capacities

The following information shall be specified:

- a) fuel tank;
- b) hydraulic system.

Other related information that may be specified includes

- c) hydraulic tank,
- d) cooling system,
- e) engine crankcase,
- f) final drive case,
- g) pump drives, and
- h) swing drive case.

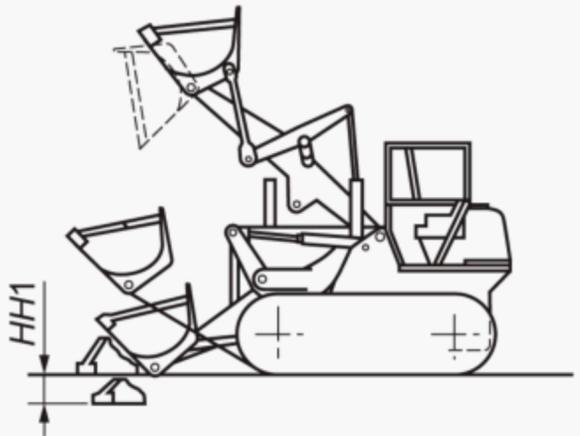
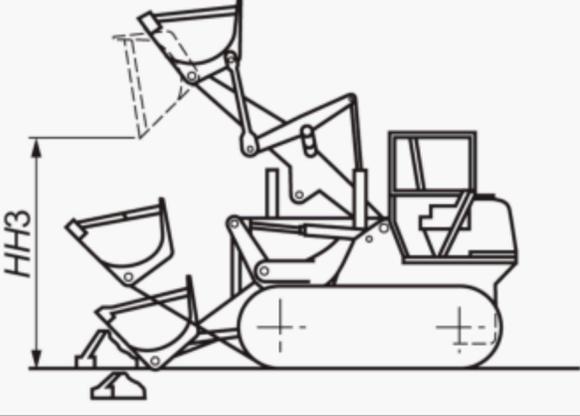
7.10 Masses

The operating mass and the shipping mass shall be specified.

Annex A (normative)

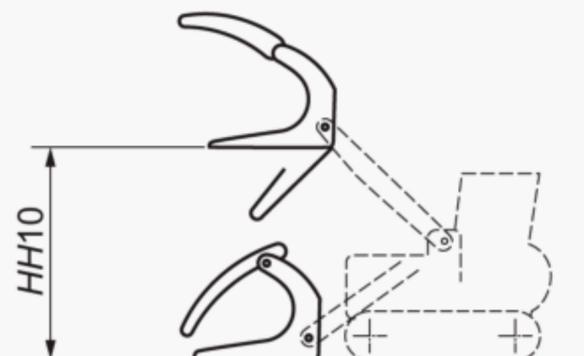
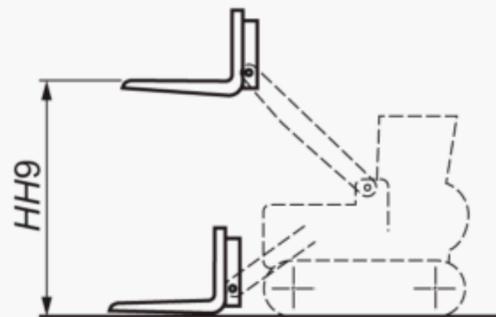
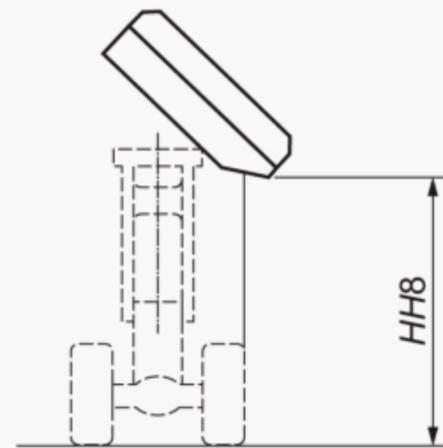
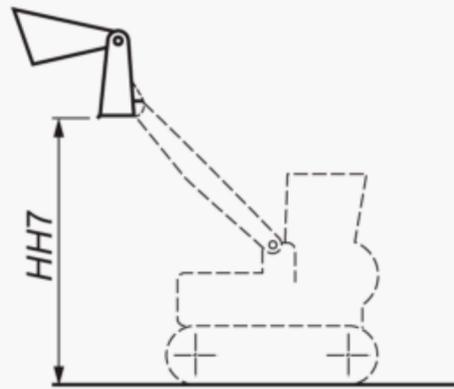
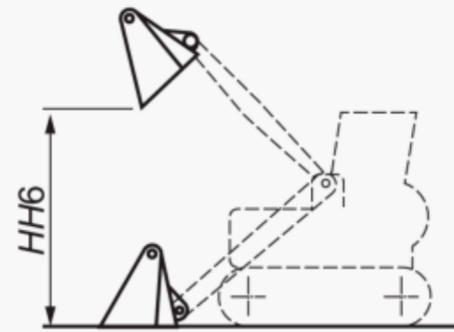
Loader equipment and attachments - Dimensions

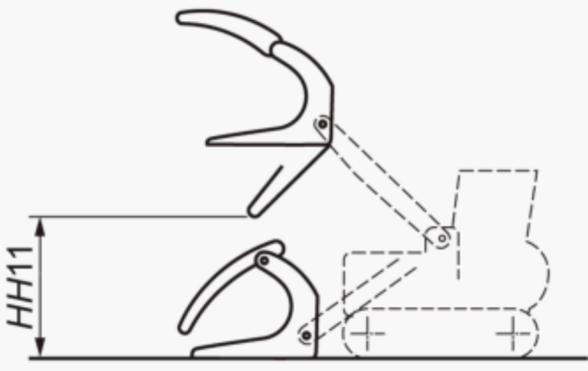
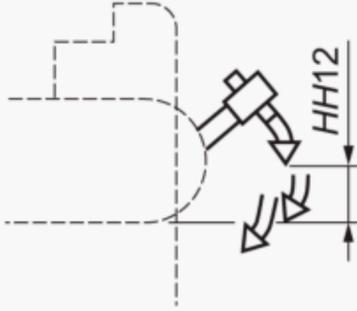
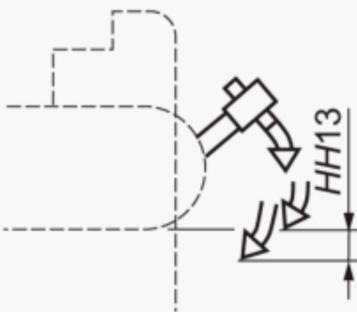
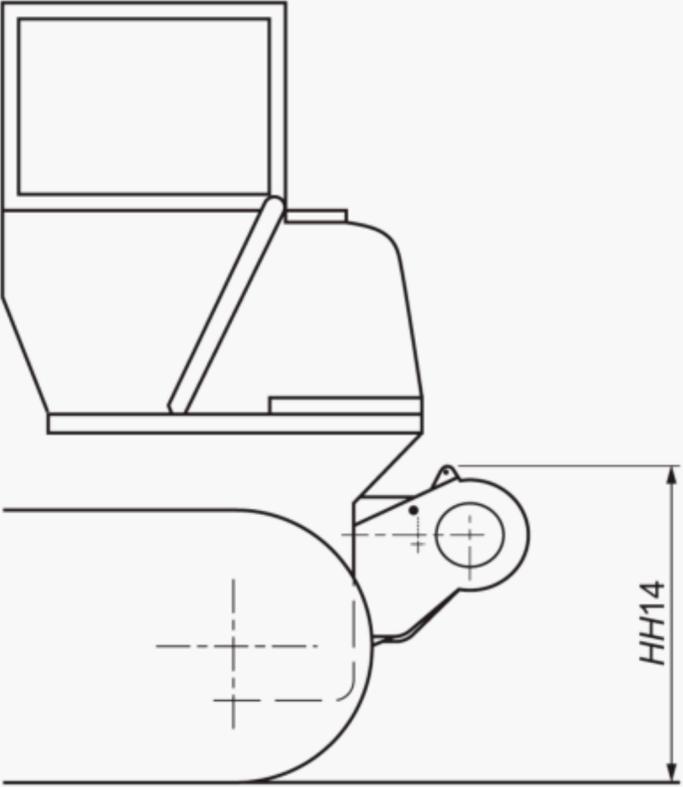
This annex defines, in accordance with ISO 6746-2, loader equipment and attachment dimensions and their identifying terms and codes (see also [Figures 18 to 24](#)).

Code	Term	Definition	Illustration
HH1	Digging depth	Distance on Z coordinate between the ground reference plane (GRP) and the bottom of the bucket cutting edge at the lowest position with the bucket cutting edge horizontal.	
HH2	Carry position (height)	Distance on Z coordinate between the GRP and the centreline of the bucket hinge pin, with the angle of approach at 15° to the lowest point of the bucket or lift arms, whichever is the lower, with the bucket at maximum rollback.	
HH3	Dump height	Distance on Z coordinate between the GRP and the lowest point of the cutting edge, with the bucket hinge pin at maximum height and the bucket at a 45° dump angle. If the dump angle is less than 45°, specify the angle.	
HH4	Height to hinge pin, fully raised	Distance on Z coordinate between the GRP and the centreline of the bucket hinge pin with a fully raised bucket.	

Code	Term	Definition
HH5	Overall operating height, fully raised	Distance on Z coordinate between the GRP and the highest point obtainable with a fully raised bucket.
HH6	Maximum dump height, clam closed	Distance on Z coordinate between the GRP and the lowest point on the bucket cutting edge, (clam closed), with the bucket hinge at maximum height and the bucket at maximum dump angle.
HH7	Maximum dump height, clam open	Distance on Z coordinate between the GRP and the lowest point on the mouldboard cutting edge (clam open), with the bucket hinge pin at maximum height and the bottom of the mouldboard section of the bucket horizontal.
HH8	Maximum dump height, side	Distance on Z coordinate between the GRP and the lowest point of the side dumping edge, with the bucket hinge pin at maximum height and the bucket at maximum side dump angle.
HH9	Maximum lift height, tines level	Distance on Z coordinate between the GRP and the upper surface of the tines, with the pallet fork hinge pin at maximum height and tines level.
HH10	Height of level tines, fully raised	Distance on Z coordinate between the GRP and the lower surface of the tines, with the fork hinge pin at maximum height and tines level.

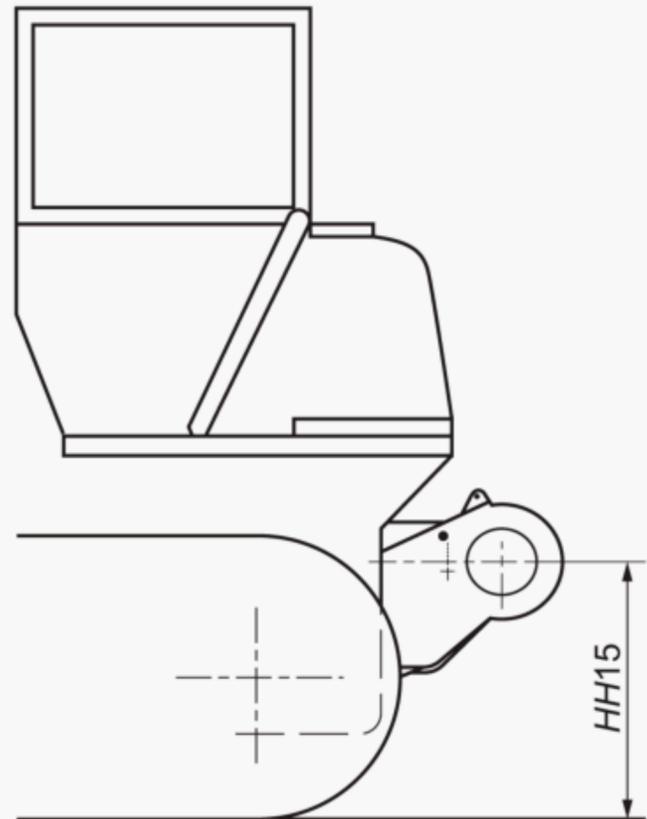
Illustration



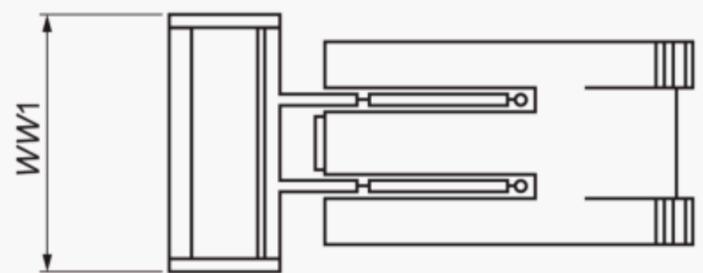
Code	Term	Definition	Illustration
HH11	Height of tips of tines, fork fully raised and dumped	Distance on Z coordinate between the GRP and the tips of the tines, with the fork hinge pin at maximum height and in dump position.	
HH12	Maximum scarifier lift height	Distance on Z coordinate between GRP and the lowest point of the cutting edge of the mid-tooth.	
HH13	Maximum scarifier depth	Distance on Z coordinate between GRP and the scarifier teeth at the deepest point that can be reached vertically.	
HH14	Maximum height of winch	Distance on Z coordinate between the GRP and the uppermost point on the winch.	

Code	Term	Definition
HH15	Height of centre point of the winch	Distance on Z coordinate between the GRP and the centreline of the winch mechanism.

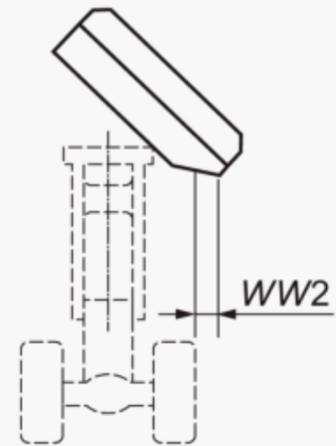
Illustration



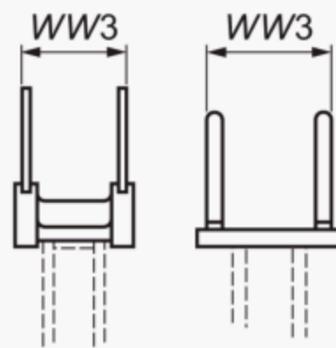
WW1	Attachment width	Distance on Y coordinate between two Y planes passing through the furthest point on the sides of the attachment.
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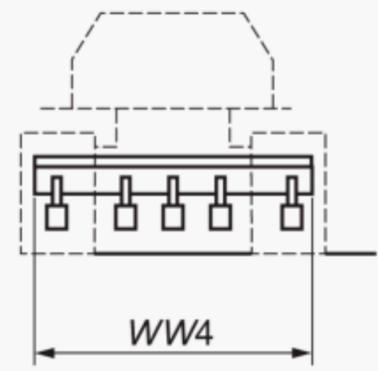
WW2	Maximum side dump reach	Distance on Y coordinate between two Y planes passing through the foremost point on the machine (including tyres, tracks or loader frames) and the foremost point on the bucket cutting edge, with the bucket hinge pin at maximum height and the bucket at maximum side dump angle.
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WW3	Tines width	Distance on Y coordinate between two Y planes passing through the outside face of the external tines.
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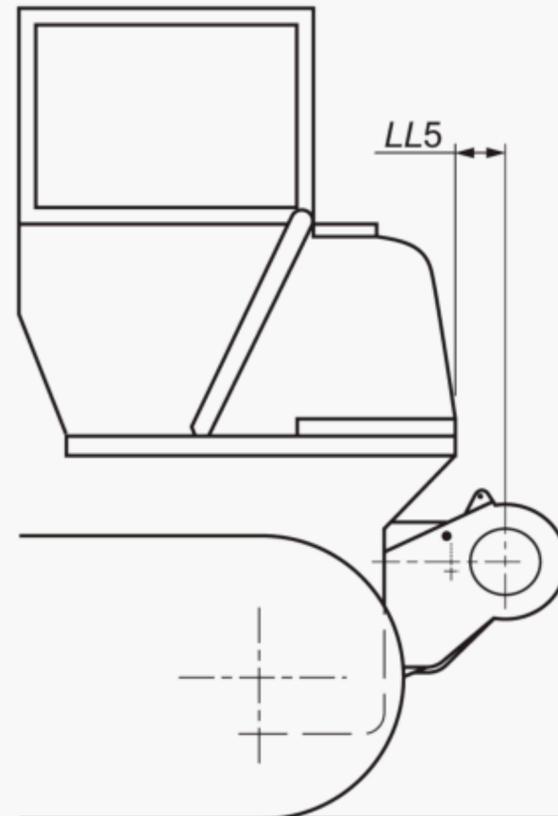
WW4	Scarifier width	Distance on Y coordinate between two Y planes passing through the furthest point on the sides of the scarifier.
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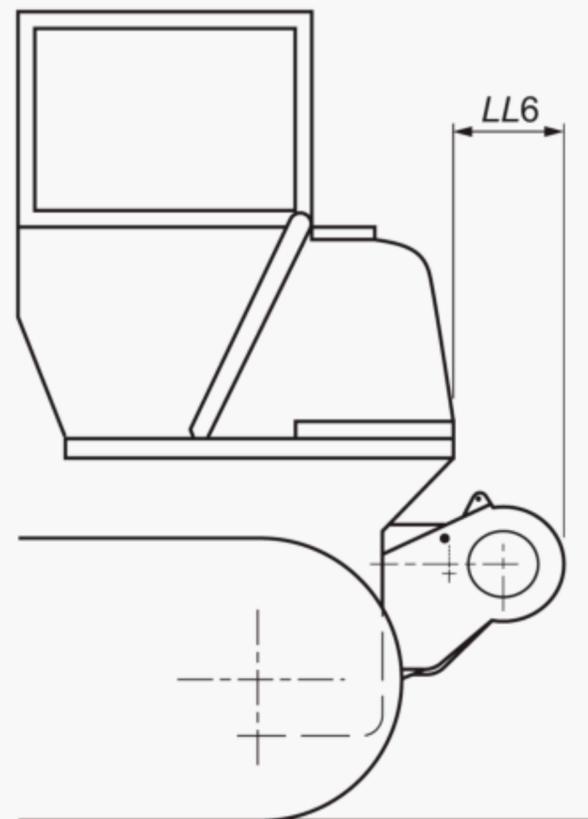
Code	Term	Definition	Illustration
WW5	Width of outer teeth of scarifier	Distance on Y coordinate between two Y planes passing through the outside face of external scarifier teeth.	
WW6	Scarifier teeth width	Distance on Y coordinate between two Y planes passing through the centre of adjacent scarifier teeth.	
LL1	Reach, fully raised	Distance on X coordinate between planes passing through the foremost point on the machine (including tyres, tracks or loader frame) and the foremost point on the cutting edge with the bucket hinge pin at maximum height and the bucket at a 45° dump angle.	
LL2	Overall length (with attachment)	Distance on X coordinate between planes passing through the rearmost point on the machine and the foremost point of the attachment with the attachment bottom on the ground and level.	
LL3	Reach, fully raised	Distance on X coordinate between two X planes passing through the foremost point on the machine (including tyres, tracks or loader frames) and the rearmost point on the bucket cutting edge tip with the bucket hinge pin at maximum height and the bucket at maximum dump angle.	
LL4	Rearmost distance of scarifier	Distance on X coordinate between two X planes passing through the rearmost point on the machine (including tyres, tracks or loader frames) and the rearmost point on the scarifier when the scarifier tooth is level with the GRP.	

Code	Term	Definition
LL5	Distance of centre point of winch from machine	Distance on X coordinate between two X planes passing through the rearmost point on the machine (including tyres, tracks or loader frames) and the centre point of the winching mechanism.

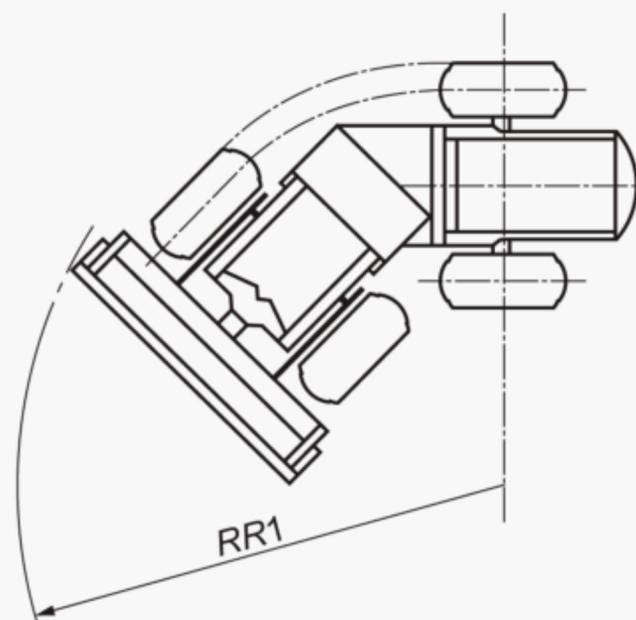
Illustration



LL6	Distance to rearmost point on attachment	Distance on X coordinate between two X planes passing through the rearmost point on the machine (including tyres, tracks or loader frames) and the rearmost point on the attachment.
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RR1	Minimum turning radius with bucket in carry position	Distance on Z plane between the turning centre and the farthest point on the side of the bucket when the machine is executing its smallest practicable turn.
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Code	Term	Definition	Illustration
AA1	Dump angle	Maximum angle that the longest flat section of the inside bottom of the bucket will rotate below horizontal with the bucket in the fully raised position.	
AA2	Maximum rollback, fully raised	Angle from the bucket cutting edge horizontal position to the maximum rollback position, lift arms fully raised.	
AA3	Maximum rollback at ground	Maximum rollback angle without movement of the lift arm, starting with the bottom of the cutting edge on the GRP.	
AA4	Maximum rollback at carry position	Angle from the bucket cutting edge horizontal position to the maximum rollback position, with lift arms in the carry position (see HH2).	
AA5	Maximum grading angle	Maximum angle that the bucket cutting edge will rotate below the horizontal with the bucket cutting edge on the GRP.	

Bibliography

- [1] ISO 5010, *Earth-moving machinery - Rubber-tyred machines - Steering requirements*
- [2] ISO 8812, *Earth-moving machinery - Backhoe loaders - Definitions and commercial specifications*

Amendment 1

[3.1](#)

Replace the definitions of the terms *loader*, *compact loader* and *skid steer loader* with the following:

3.1.1 loader

self-propelled crawler or wheeled machine having front-mounted equipment, primarily designed for loading operation (bucket use), which loads or excavates through forward motion of the machine

Note 1 to entry: A loader work cycle normally comprises filling and elevating, and the transporting and discharging of material.

[ISO 6165:2012, definition 4.2]

3.1.1.1 compact loader

loader (3.1.1) having an *operating mass* (3.2.1) of 4 500 kg or less for wheeled loaders and 6 000 kg or less for crawler loaders, designed to work in areas with limited space, with the associated need for greater manoeuvrability

Note 1 to entry: The general term *compact machine* is defined in ISO 6165.

[ISO 6165:2012, definition 4.2.3]

3.1.1.2 skid steer loader

loader (3.1.1) normally having an operator station between or to the side of the attachment-supporting structure(s) and steered by using variation of speed, and/or direction of rotation between traction drives on the opposite sides of a machine having fixed axles on wheels or tracks

[ISO 6165:2012, definition 4.2.2]

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